

## **RDE-Testmatrix on an engine testbed with virtual components – model based testing in the engine development**

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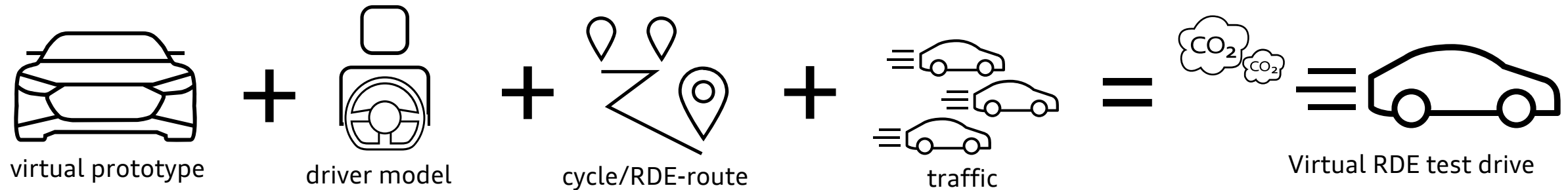
# Challenges of RDE-legislation

## Vehicle tests on public roads with everyday traffic

- > High number of different influences and conditions (driver, traffic, weather, ...)
- > Huge effort for vehicle testing
- > In case of dataset changes, no repeatability

**→ Demand for new RDE-testing methods**

## Vehicle testing on the engine testbed with virtual components



# Testing environment similar to vehicle setup

## Coldstart

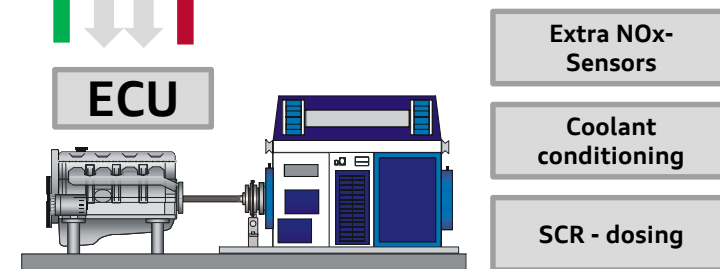
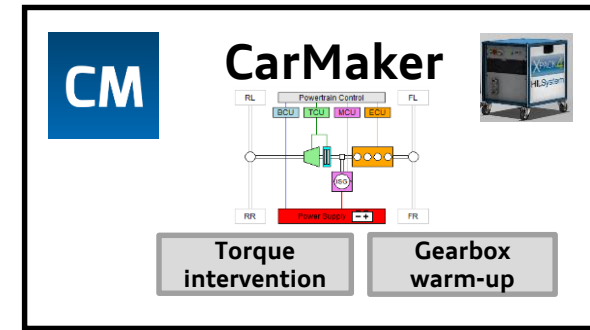
- > Oil and coolant conditioning
- > Gearbox warm-up model

## Testbed automation

- > 24/7 ready for use
- > Automatic conditioning of exhaust gas system
- > ....

## Engine ECU dataset

- > No special testbed dataset
- > Deactivation of non-existing components (eg. airbag, ...)



Source: AVL, IPG

# Integration of real road data and traffic

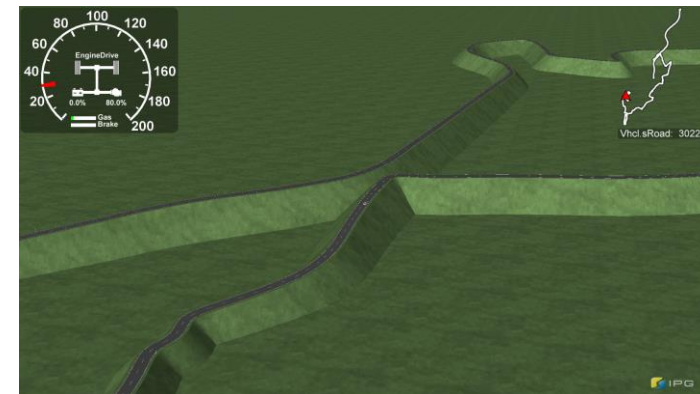
## Road

- › Current RDE-route (HRK, „Heilbronner-Rundkurs“)
- › Export from ADASRP including
  - › Traffic lights
  - › Speed limits
  - › Grades
  - › Curves

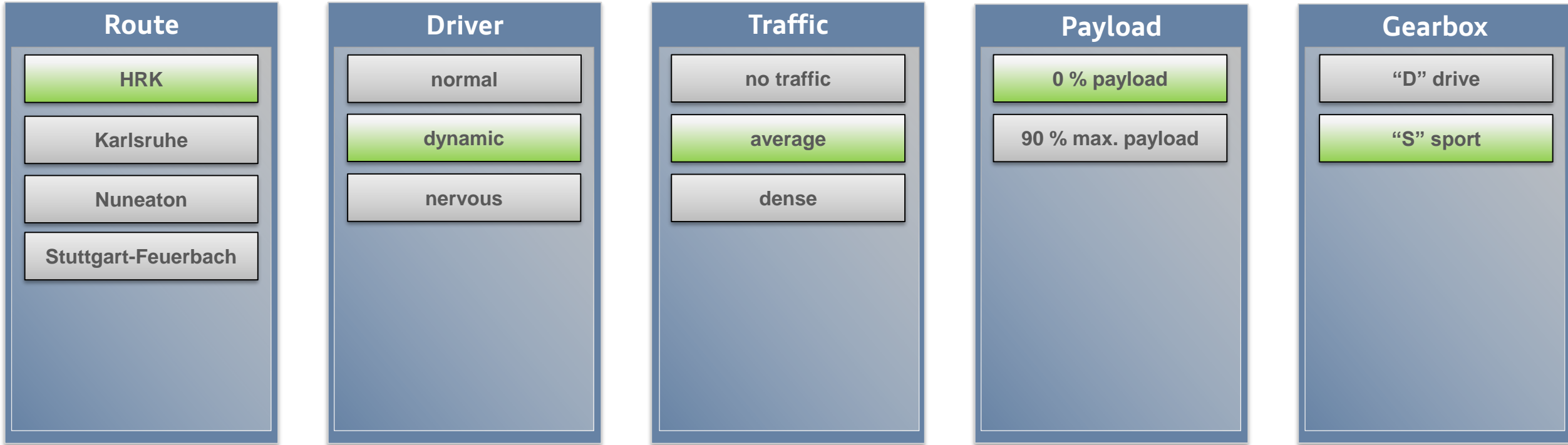


## Traffic

- › Traffic simulation using speed limits with RDx Testgenerator

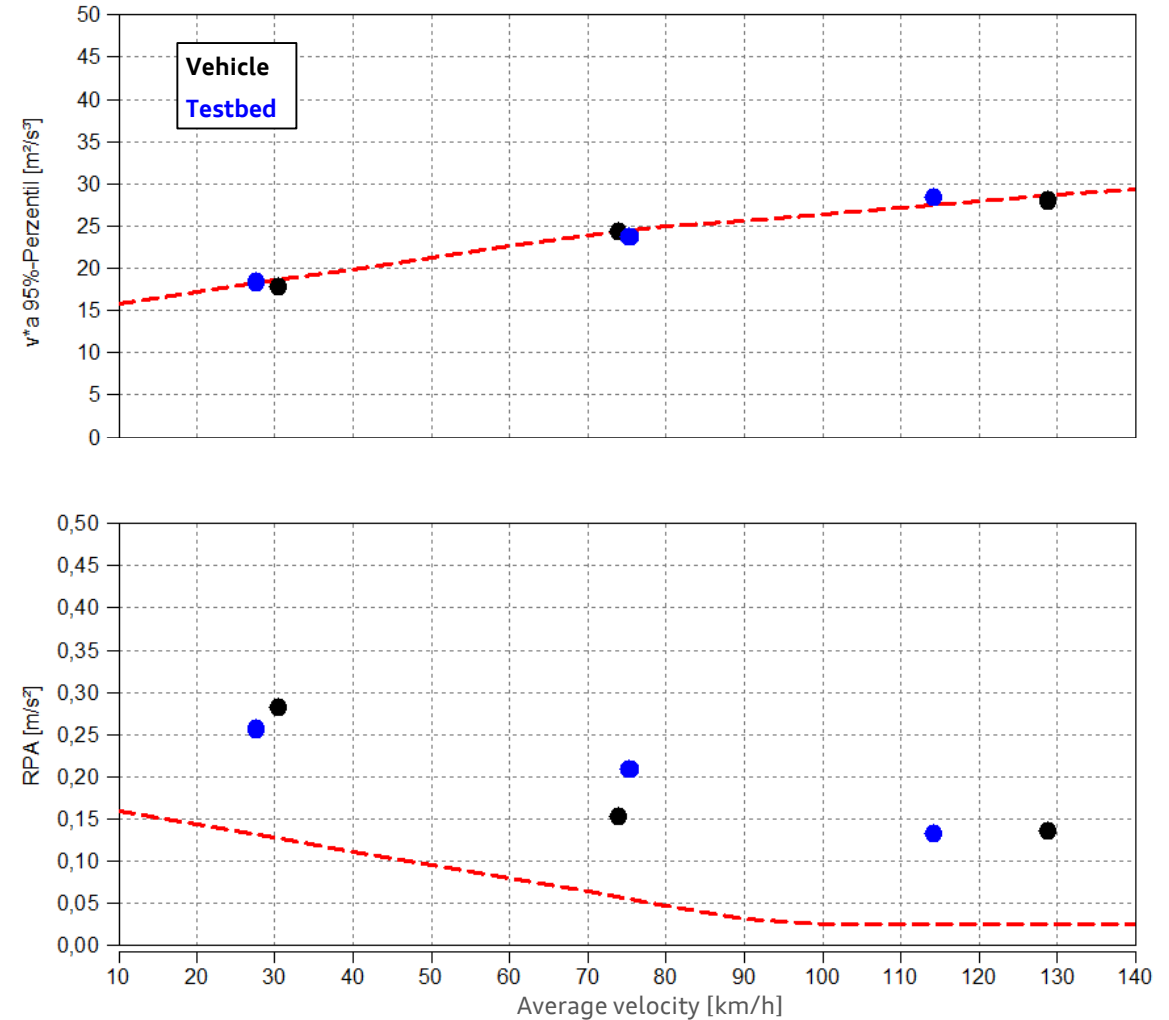


# Testmatrix allows many variations of the reference measurement



# Good match of $v^*_{apos}$ 95% percentile

- > Testbed  $v^*_{apos}$  values close to target
- > Simulated Autobahn traffic density is too high

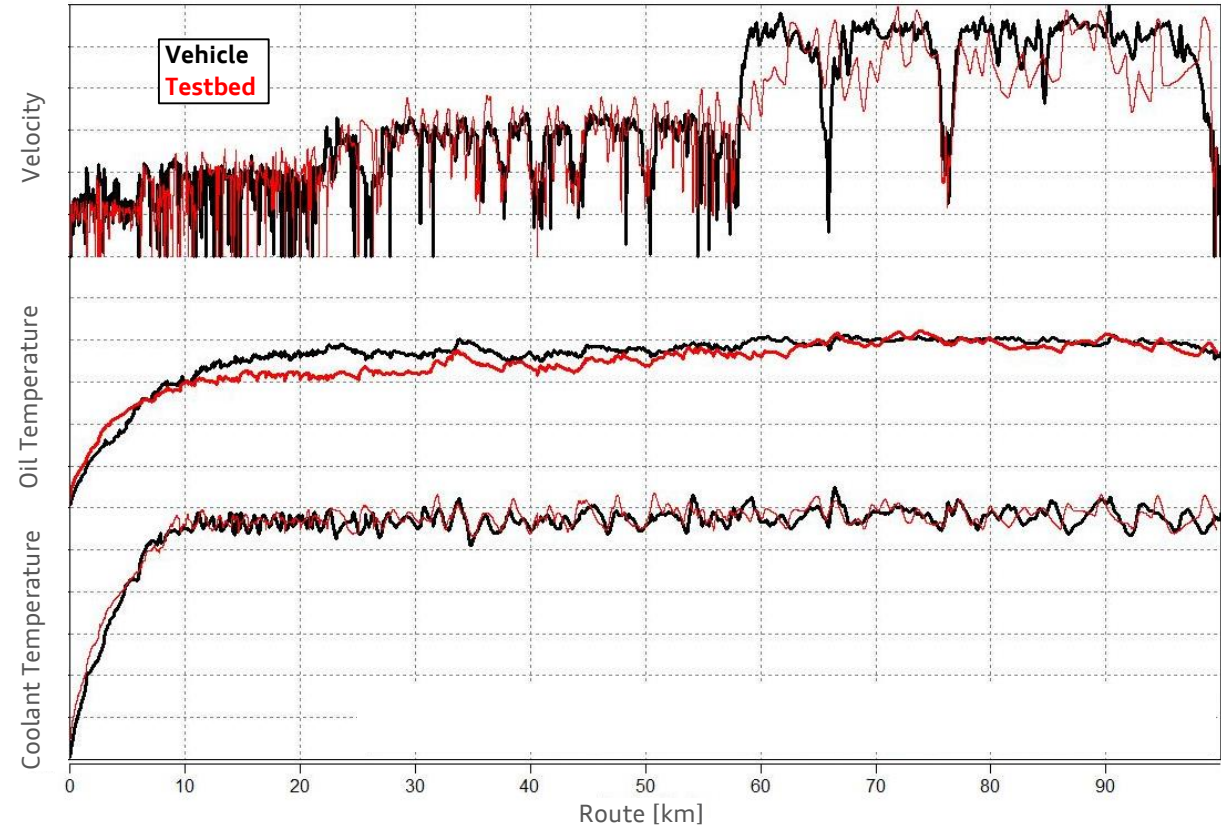


$v^*_{apos}$  = product of velocity and positive acceleration

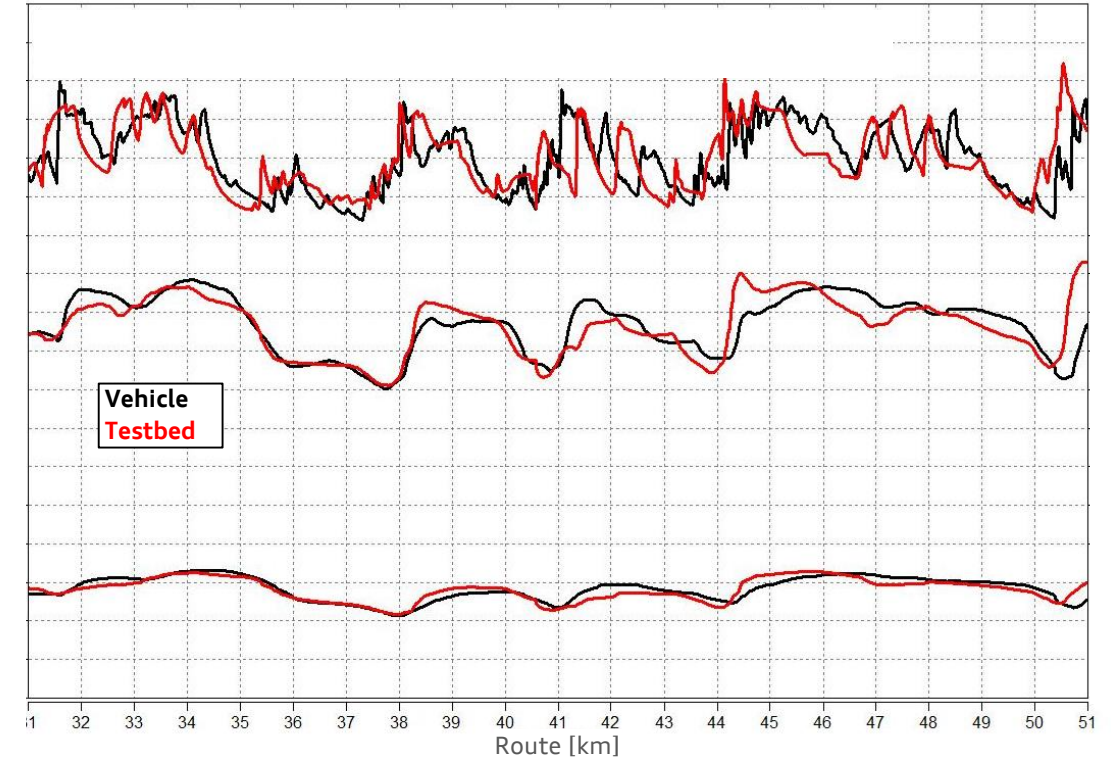
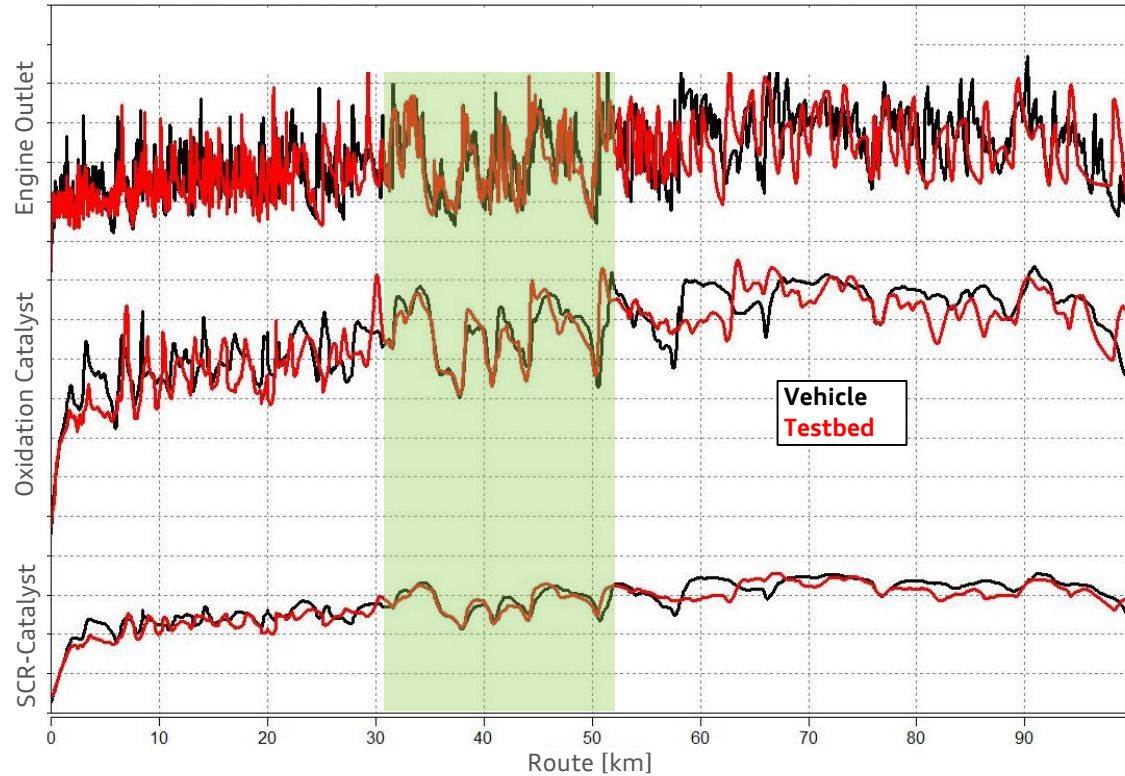
RPA = relative positive acceleration

# Cold start behaviour similar to vehicle

- › Small differences in oil temperature and good match for coolant temperature



# Similar exhaust-gas temperatures in vehicle and testbed



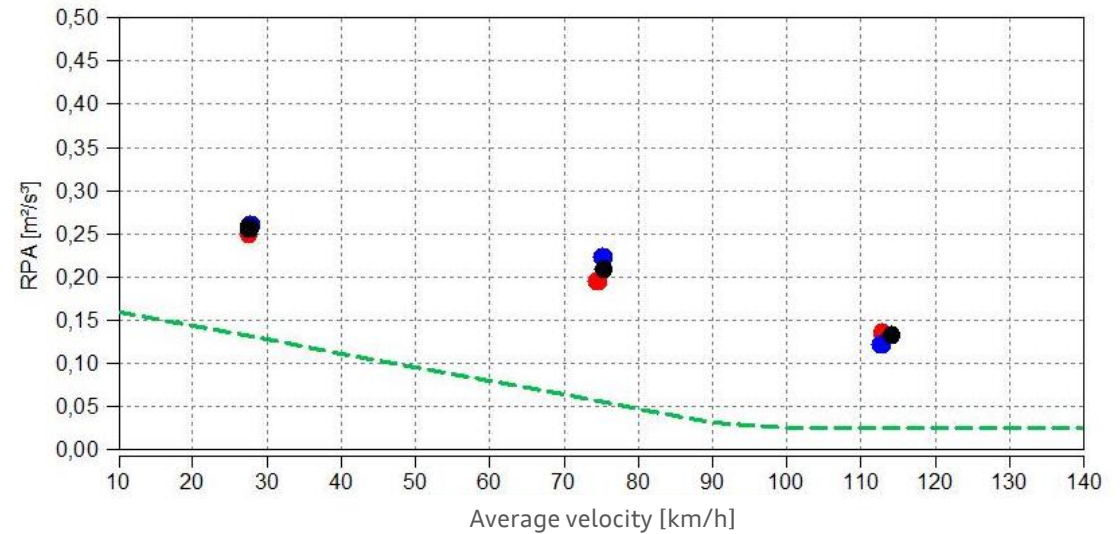
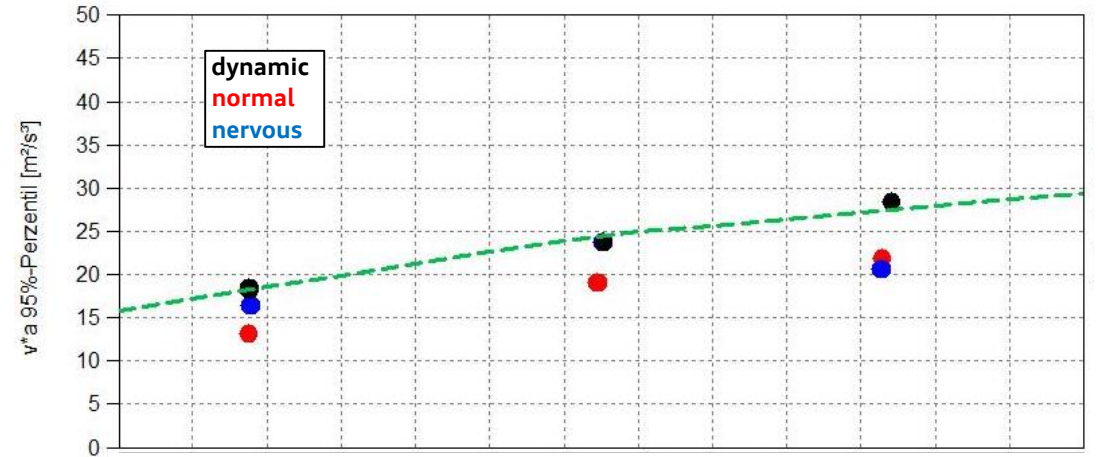
➤ Very good match to the reference measurement despite differences in environmental temperature

→ Successful transfer of vehicle measurement to testbed



# Driver variation shows influence on $v^*$ apos values

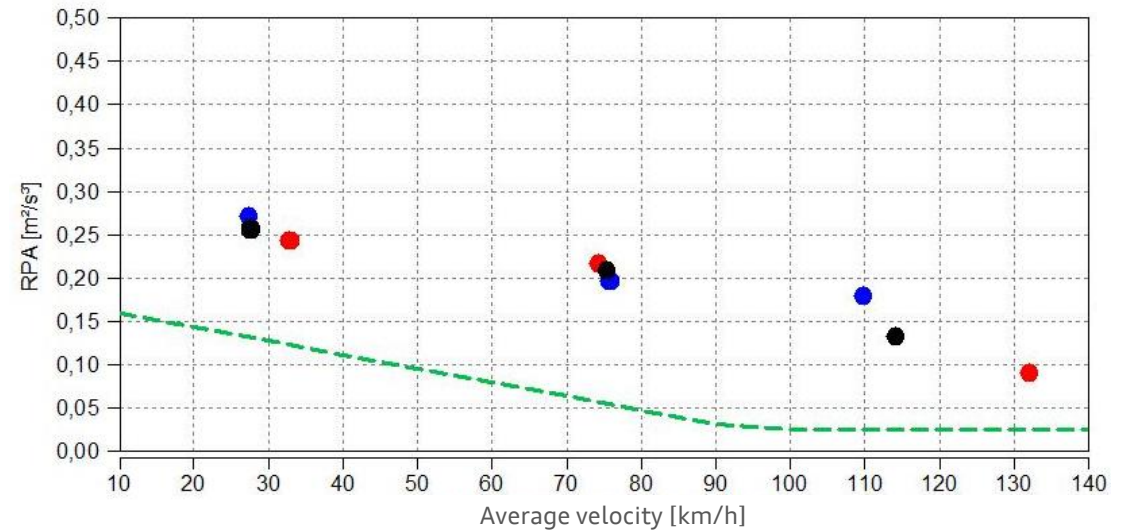
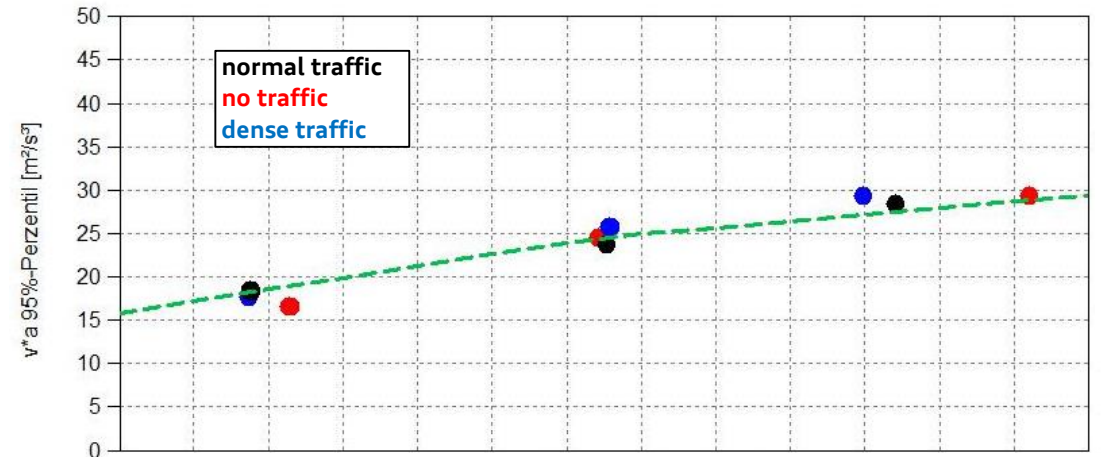
- › All parameters have been fixed except of driver
- › Acceptable values for normal and nervous driver



# Minor impact on $v^*$ apos from traffic variation

- > Main impact of the traffic density is on the average velocity
- > Minor impact on  $v^*$ apos

→ Driver causes main impact on  $v^*$ apos



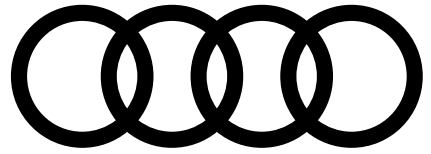
# Summary

## RDE-matrix on an engine testbed

- › Feasibility shown in a pilot project
- › Good results for the transfer of a reference measurement
- › Variation of different parameters works well

## Next steps

- › Exact replay of a reference measurement
- › Coupling with vECU (gearbox control, etc)



Thank You